HUSKY OBSERVER



UNMANNED GROUND VEHICLE



FEATURES

OPERATE WITH EASE

Navigate various environments with builtin cameras and have the freedom to operate your robot over the internet.

DATA COLLECTION

Specify repeatable autonomous missions to perform inspection and gather data through graphical user interface.

INSPECTION READY

Capture high quality data with built-in pan-tilt-zoom camera, microphone, and optional thermal camera.

CUSTOMIZABLE

Add up to 10 kg of payload. Leverage ROS API for full control of the system and build your own user interface.

INDUSTRIES



OIL & GAS



SECURITY



MANUFACTURING



CONSTRUCTION



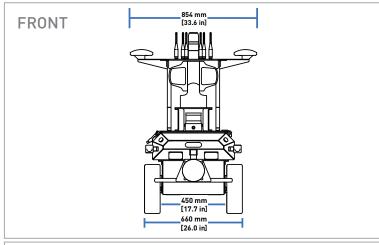
POWER & UTILITIES



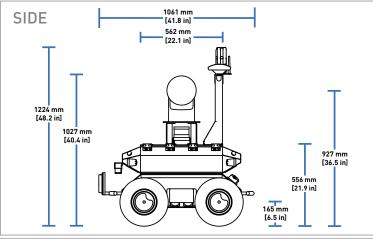
AGRICULTURE



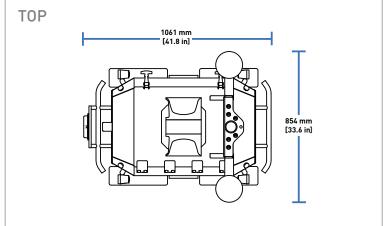
TECHNICAL SPECIFICATIONS



PLATFORM	
EXTERNAL DIMENSIONS	1061 x 854 x 1224 mm (41.8 x 33.6 x 48.2 in)
WEIGHT	98.5 kg (217 lbs)
MAXIMUM SPEED	1.0 m/s (2.3 mph)
GROUND CLEARANCE	130 mm (5 in)
OPERATING AMBIENT TEMPERATURE	-10 to +40° C
INGRESS PROTECTION	Designed for IP55
OPERATING TIME	2.5 to 4.0 hours
NETWORKING	WiFi + Cell (LTE)
WIRELESS CHARGING	Up to 300W



INSPECTION SENSORS	
PTZ CAMERA	1920 x 1080 video/image resolution, 31x optical zoom, IR illumination up to 400 m
MICROPHONE	20 Hz to 10 kHz range, -22 dB sensitivity, 126 dB max SPL, 82 dBA SNR
OPTIONAL THERMAL CAMERA	640 x 480 resolution, up to 42° FOV, video + radiometric streaming, motorized focus control



NAVIGATION SENSORS	
FRONT / REAR DEPTH CAMERAS	1280 x 720 active stereo depth resolution (90 FPS max), 1920 x 1080 RGB (30 FPS max)
FRONT 2D LIDAR / OPTIONAL REAR 2D LIDAR	0.02 - 10m range, 40Hz, 270° FOV, 0.25° resolution
3D LIDAR	16 channels, measurement range: up to 100 m, accuracy: ±3 cm (typical)
ATTITUDE AND HEADING REFERENCE SYSTEM (AHRS)	±8g accel range, ±300 °/sec gyro range, ±0.5° static roll/pitch/heading, ±2.0° dynamic roll/pitch heading, 0.2° repeatability, <0.1° resolution, 1000 Hz output rate
RTK GPS	Localization within 5 cm or less

CONTACT US FOR MORE INFORMATION

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Don't forget to find us online:









